

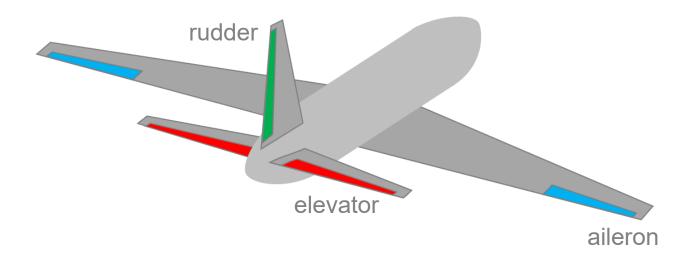
THERMOHYDRAULIC MODELING OF AN ELECTRO-HYDRAULIC SERVO ACTUATOR ON DAMPED MODE

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- Hydraulic powered flight control systems are widely used in aviation
- The primary surfaces are essential for aircraft control and must meet safety requirements







Smaller, lighter and more efficient

→ Flutter criteria and dynamic requirements

Temperature and thermal effects

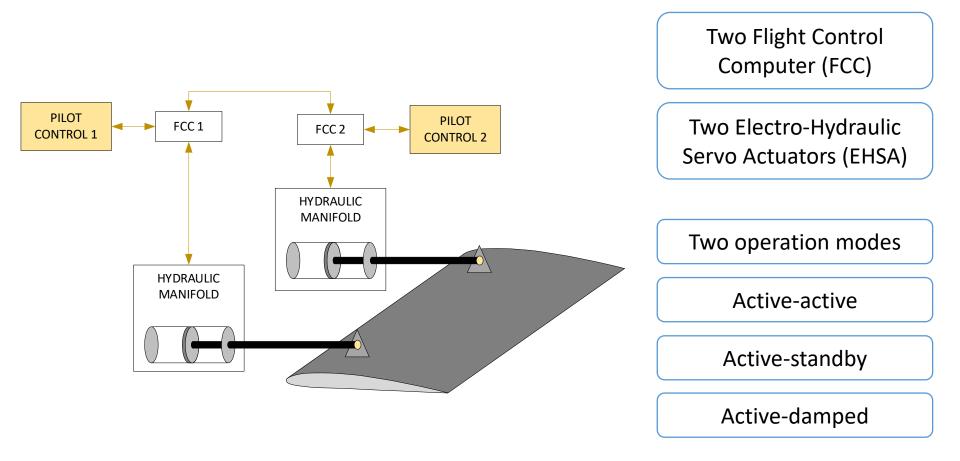


 This study focuses on modeling the thermal behavior of the main components of a flight control system in the damped operation of a civil aircraft



Flight Control System Architecture

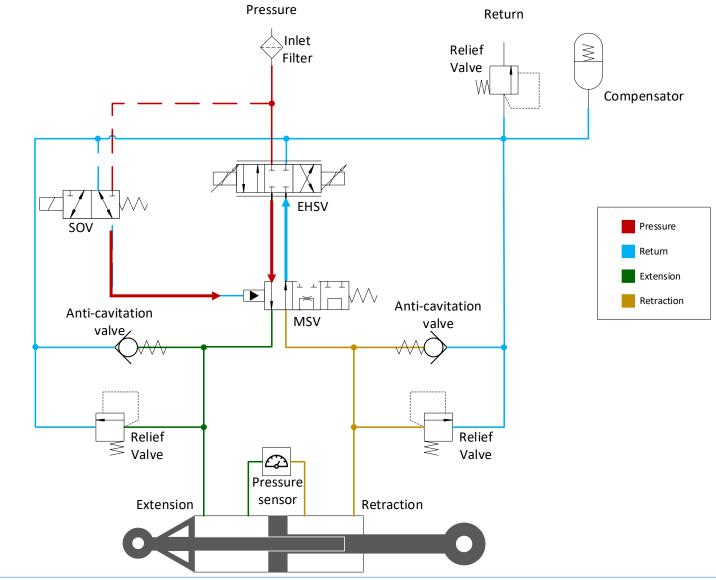






Active Operation

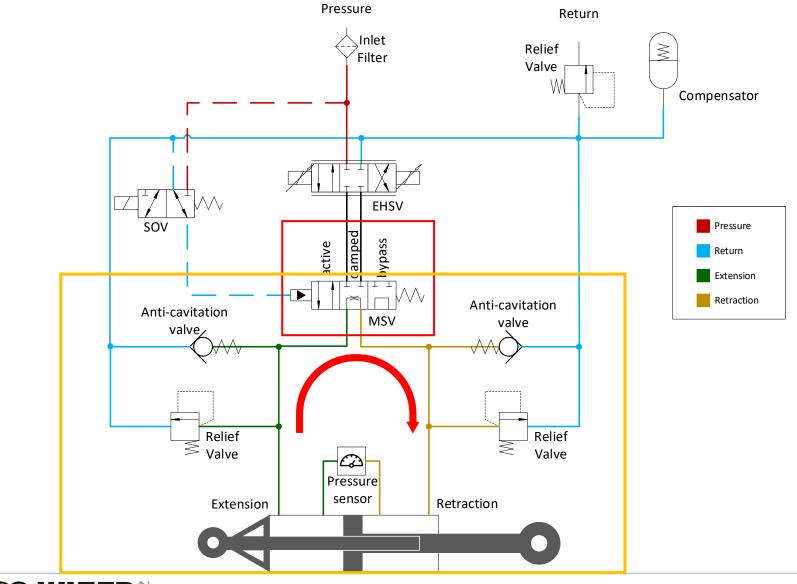






Damped Operation

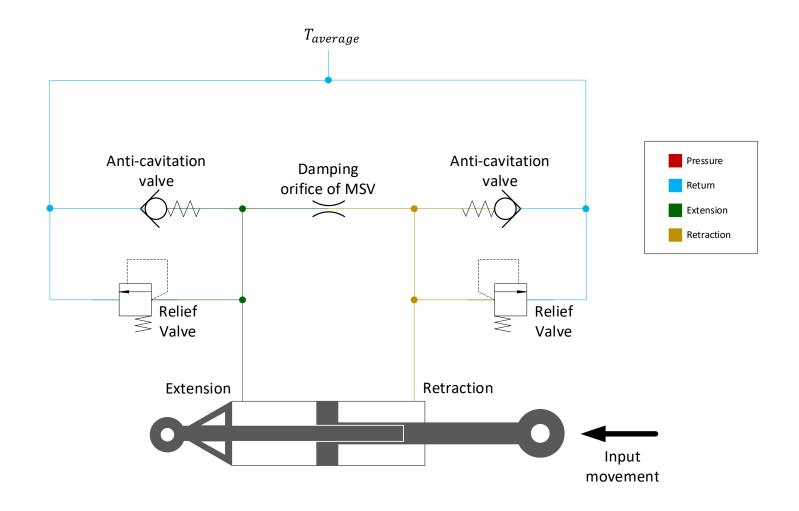






Actuation Architecture







Resistive Elements



Mass flow

$$\dot{m} = \rho \cdot c_q \cdot A \cdot \sqrt{\frac{2}{\rho}(p_1 - p_2)}$$

• Temperature increase

$$\frac{dh}{dt} = c_p \frac{dT}{dt} + \frac{(1 - \alpha T)}{\rho} \frac{dp}{dt}$$
$$T_{out} = T_{in} + \frac{(1 - \alpha T_{in}) \cdot |\Delta p|}{\rho \cdot c_p}$$





• Pressure variation

$$d\rho = \left(\frac{\partial\rho}{\partial p}\right)_{T} dp + \left(\frac{\partial\rho}{\partial T}\right)_{p} dT$$
$$\alpha(p, T) = -\frac{1}{\rho} \cdot \frac{\partial\rho}{\partial T}$$
$$\beta_{t} = -V \cdot \frac{\partial p}{\partial V} = \rho \frac{\partial p}{\partial \rho}$$
$$\frac{dp}{dt} = \beta \left(\frac{\Sigma(\dot{m}) - \rho \frac{dV}{dt}}{\rho V} + \alpha \frac{dT}{dt}\right)$$





• Temperature variation

$$\begin{aligned} \frac{dE}{dt} &= \dot{Q} - p \frac{dV}{dt} + \sum \dot{m} h \\ \frac{dE}{dt} &= \frac{dU}{dt} = \frac{d(mh - pV)}{dt} \\ \frac{dh}{dt} &= c_p \frac{dT}{dt} + \frac{(1 - \alpha T)}{\rho} \frac{dp}{dt} \\ \frac{dT}{dt} &= \frac{\dot{Q} + \Sigma(\dot{m}h_i) - h \cdot \Sigma(\dot{m})}{\rho \cdot c_p \cdot V} + \frac{\alpha \cdot T}{\rho \cdot c_p} \frac{dp}{dt} \end{aligned}$$





• Total thermal resistance and equivalent capacitance

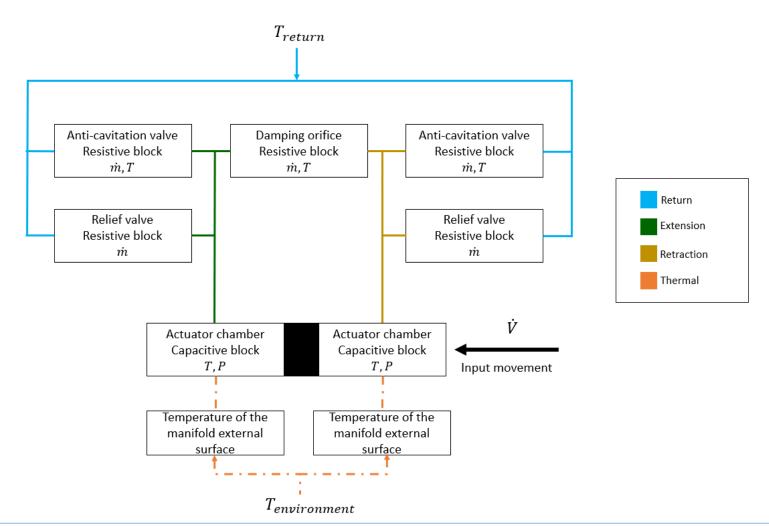
$$R_{tot} = \sum R = \frac{\Delta T}{\dot{Q}} = \frac{1}{U_t A}$$

$$\frac{dT}{dt} = \frac{\sum \dot{Q}}{mc_p} = \frac{\sum \dot{Q}}{C_t}$$





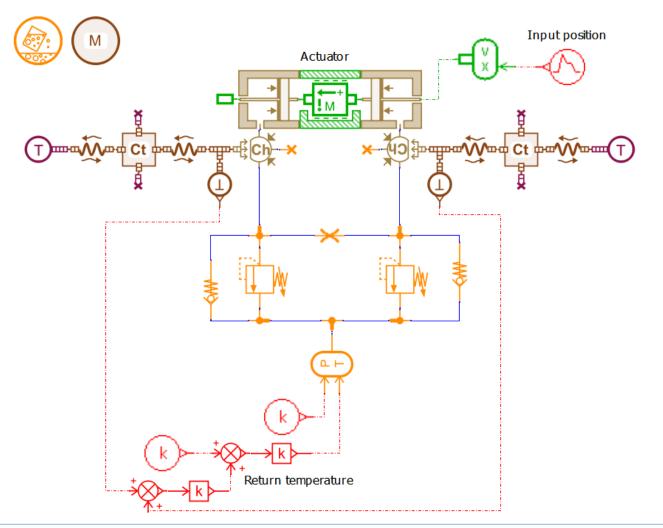
• Building blocks in MATLAB/Simulink







• Building blocks in AMESIM

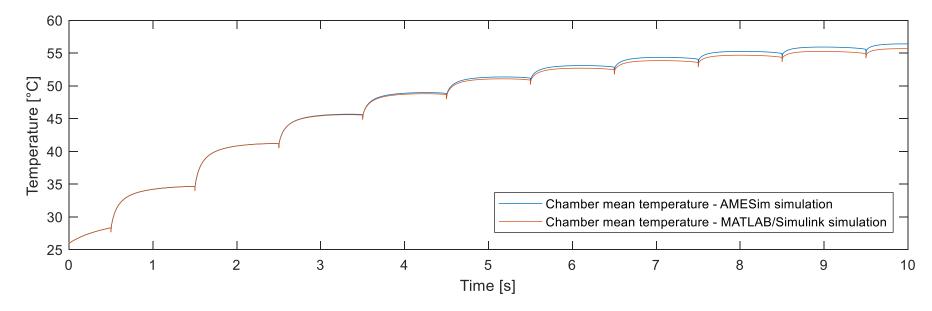








- Both software achieved similar behaviors
- 1.3% of variation after 10s
- Fluid modeling: standard SAE AS1241 and built-in

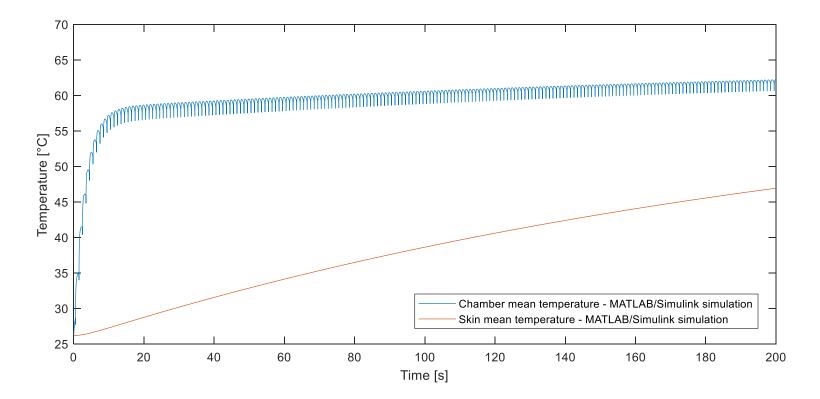








- Cases evaluated did not induce overheating
- Different test conditions are possible with the model







- Both models achieved satisfactory results
- The models can simulate the temperature of the manifold
- The thermohydraulic blocks can be reused

Future Assessments:

- To evaluate the heat transfer inside the manifold
- To compare the results achieved with data from tests to verify hypothesis and thermal coefficients
- To perform a sensitivity analysis regarding the temperature impacts of each design change
- To perform a parametric identification to fit the models





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